

Sensitive study of numerical simulation of wedge failure

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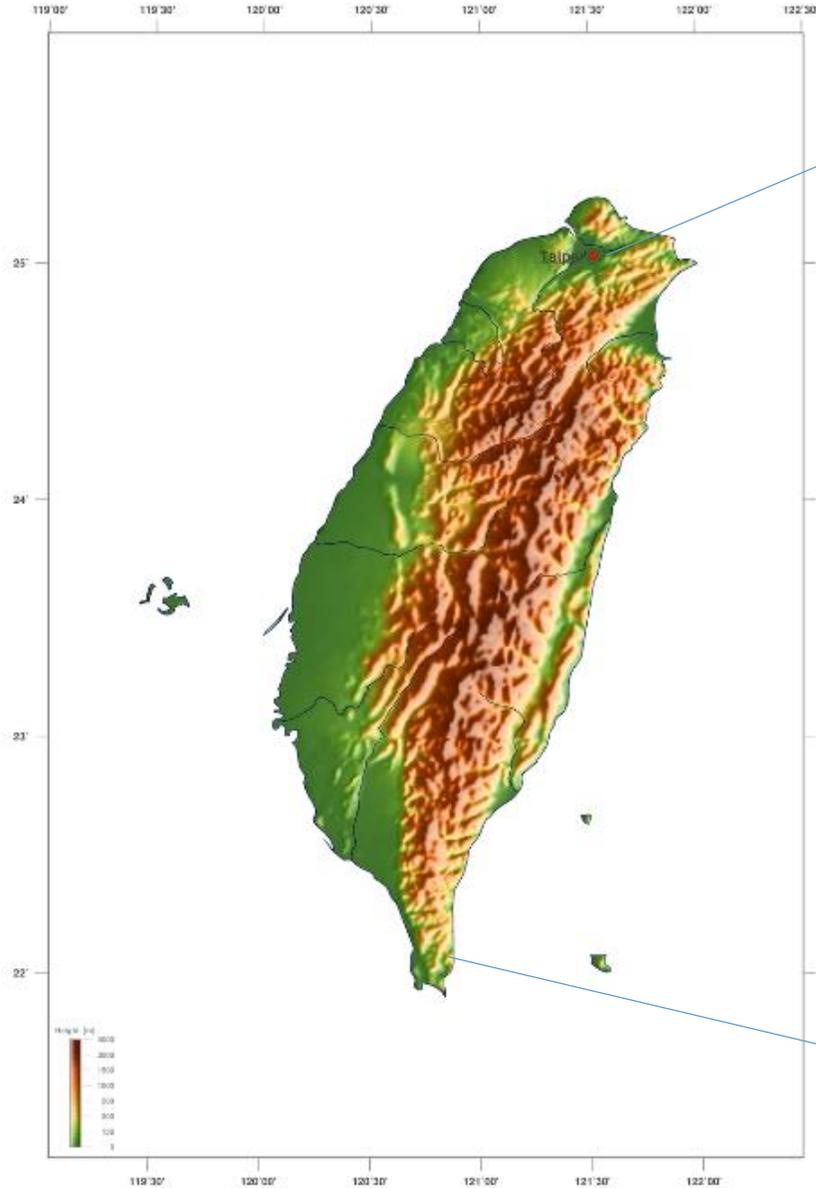
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outline

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3. Method
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5. Preliminary Summary
6. Future work

Introduction

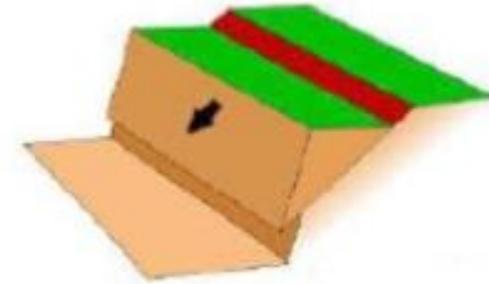


Plane
cover area
26.36%
in Taiwan

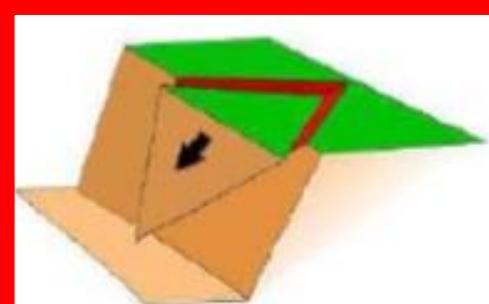
Hillside
cover area
26.91%
in Taiwan

High mountain
cover area is
46.73%
in Taiwan

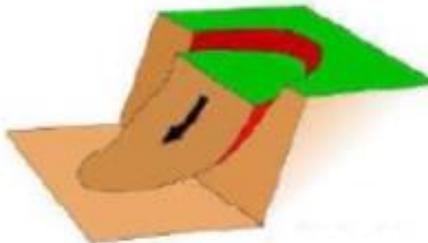
Type of slope failure



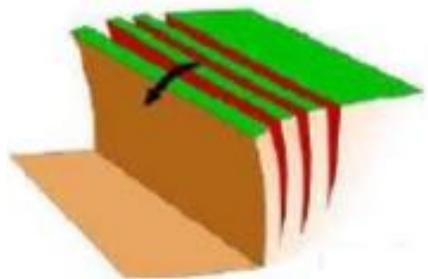
planer failure



wedge failure

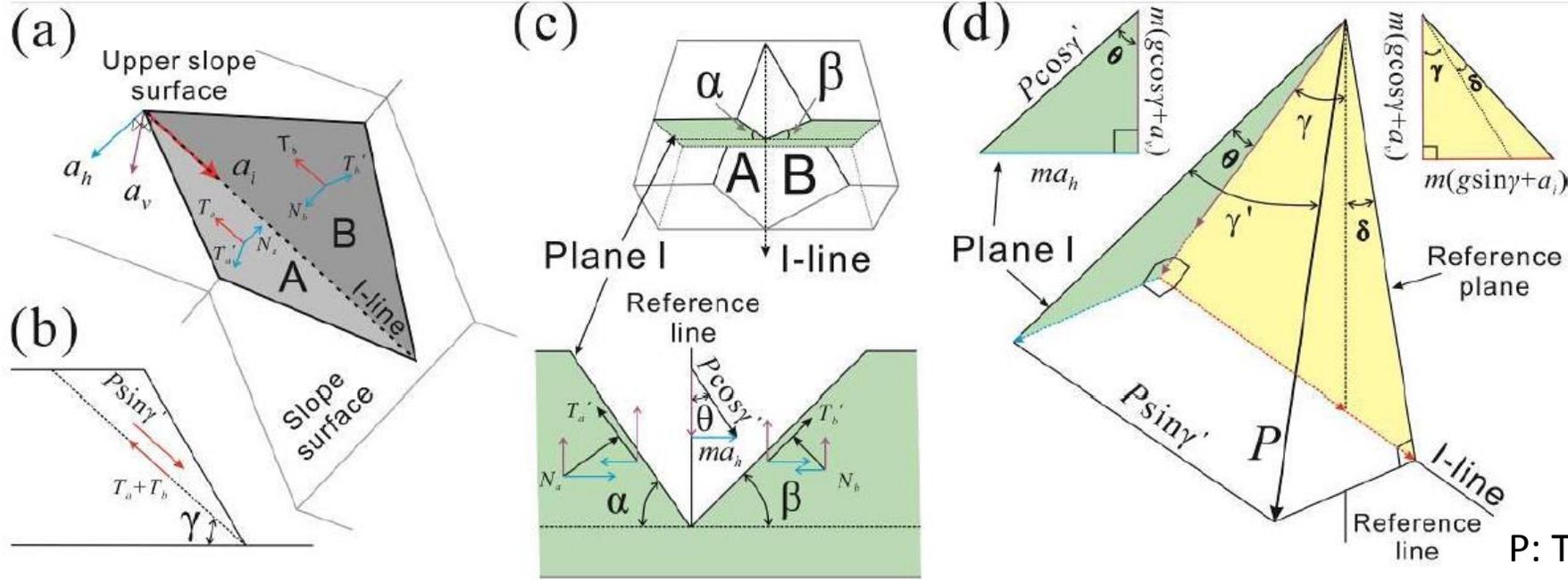


circular failure



topple failure

Introduction



Nguyen,2015(modified from Lee,1989)

P: The resultant force P

N_a/N_b : normal force of plane A/B

T'_a/T'_b : shear stress perpendicular to I-line on plane A/B

γ : the plunge of of I-line

θ : parameters used to define direction of vector force P

α : the plunge of intersection line with plane A on plane I

β : the plunge of intersection line with plane B

$$N_a \sin \alpha + T'_a \cos \alpha + T'_b \cos \beta - N_b \sin \beta = P \cos \gamma \cos \theta$$

$$N_a \cos \alpha + T'_a \sin \alpha + T'_b \sin \beta - N_b \cos \beta = P \cos \gamma \sin \theta$$

4 parameters are unknown, only 2 equation!!!

Introduction-Rigid wedge method (RWM)(Hoek and Bray,1974)

assumed the wedge is a rigid block and neglected the shear forces that perpendicular to I-line on two discontinuities T_a' and T_b'

$$T_a' = T_b' = 0$$

$$N_a = \frac{W \cos \gamma \sin(\beta + \theta)}{\sin(\alpha + \beta)}$$

$$N_b = \frac{W \cos \gamma \sin(\alpha - \theta)}{\sin(\alpha + \beta)}$$

$$T_a' = C_a A_a + N_b \tan \varphi' = 0$$

$$T_b' = C_b A_b + N_a \tan \varphi' = 0$$

- $(\alpha - \theta)$ and $(\beta + \theta)$ are limited from 0° to 90° . otherwise it would be planar failure.
- $(\alpha + \beta)$ have to be restricted between 0° and 180° .
- $FS = \frac{\text{resist force}}{\text{driving force}} = \frac{T_a + T_b}{W \sin \gamma}$

W: rock weight

N_a/N_b : normal force of plane A/B

T_a'/T_b' : shear stress perpendicular to I-line on plane A/B

T_a/T_b : shear stress along I-line on plane A/B

γ : the plunge of of I-line

θ : parameters used to define direction of vector force P

α : the plunge of intersection line with plane A on plane I

β : the plunge of intersection line with plane B

φ' : friction angle perpendicular to I-line on plane A/B

Introduction-Maximum shear stress method (MSSM)(Lee,1989)

$$T'_a = T'_b = T_a = T_b = T_{max}$$

$$T'_a = C_a A_a + N_b \tan \varphi'$$

$$T'_b = C_b A_b + N_a \tan \varphi'$$

$$N_a = \frac{N_b D_3 + E_1 - E_3}{D_1}, \quad N_b = \frac{D_1(E_5 - E_2 - E_4) - D_2(E_1 - E_2)}{D_1 D_4 + D_2 D_3}$$

$$D_1 = \sin(\alpha - \theta) - R_a \tan \varphi \cos(\alpha - \theta) \quad E_1 = C_a A_a \cos(\alpha - \theta)$$

$$D_2 = \cos(\alpha - \theta) + R_a \tan \varphi \sin(\alpha - \theta) \quad E_2 = C_a A_a \sin(\alpha - \theta)$$

$$D_3 = \sin(\beta + \theta) - R_b \tan \varphi \cos(\beta + \theta) \quad E_3 = C_b A_b \cos(\beta + \theta)$$

$$D_4 = \cos(\beta + \theta) + R_b \tan \varphi \sin(\beta + \theta) \quad E_4 = C_b A_b \sin(\beta + \theta)$$

$$E_5 = W \cos \gamma$$

$$FS = \frac{\text{resist force}}{\text{driving force}} = \frac{C_a A_a + C_b A_b + N_a \tan \varphi + N_b \tan \varphi}{W \sin \gamma}$$

W: rock weight

N_a/N_b : normal force of plane A/B

T'_a/T'_b : shear stress perpendicular to I-line on plane A/B

T_a/T_b : shear stress along I-line on plane A/B

γ : the plunge of of I-line

θ : parameters used to define direction of vector force P

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β : the plunge of intersection line with plane B

φ' : friction angle perpendicular to I-line on plane A/B

C_a/C_b : cohesion of material on plane A/B

Introduction(Nguyen,2018)

$$T' = RT_{max}(R=0-1) \quad \begin{aligned} T_a' &= R(C_a A_a + N_b \tan \varphi') \\ T_b' &= R(C_b A_b + N_a \tan \varphi') \end{aligned}$$

$$N_a = \frac{N_b D_3 + E_1 - E_3}{D_1}, \quad N_b = \frac{D_1(E_5 - E_2 - E_4) - D_2(E_1 - E_2)}{D_1 D_4 + D_2 D_3}$$

$$\begin{aligned} D_1 &= \sin(\alpha - \theta) - R_a \tan \varphi \cos(\alpha - \theta) & E_1 &= R_a C_a A_a \cos(\alpha - \theta) \\ D_2 &= \cos(\alpha - \theta) + R_a \tan \varphi \sin(\alpha - \theta) & E_2 &= R_a C_a A_a \sin(\alpha - \theta) \\ D_3 &= \sin(\beta + \theta) - R_b \tan \varphi \cos(\beta + \theta) & E_3 &= R_b C_b A_b \cos(\beta + \theta) \\ D_4 &= \cos(\beta + \theta) + R_b \tan \varphi \sin(\beta + \theta) & E_4 &= R_b C_b A_b \sin(\beta + \theta) \\ & & E_5 &= W \cos \gamma \end{aligned}$$

$$FS = \frac{\text{resist force}}{\text{driving force}} = \frac{C_a A_a + C_b A_b + N_a \tan \varphi + N_b \tan \varphi}{W \sin \gamma}$$

W: rock weight

N_a/N_b : normal force of plane A/B

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Motivation

- Because RWM and MSSM provide **factor of safety upper** and **lower** boundary, they show the **lowest** and **highest** shear stress which is perpendicular to I line. It also mean different deformable condition of wedge block. RWM regard the wedge block as rigid block and MSSM regard the wedge as the most deformable block. Therefore, this study want to know **what kind of deformable condition is suitable for RWM and MSSM on different dihedral angle**

Method-Flac 3D

- FLAC3D (Fast Lagrangian Analysis of Continua in 3 Dimensions)
- A numerical modeling code for advanced geotechnical analysis of soil, rock, and structural support in three dimensions
- Use **finite-difference methods (FDM)** to get solution .
- The calculation cycle repeats over-and-over until a steady-state solution has been achieved(i.e the maximum unbalanced force is small compared to the total applied forces)

Method-Flac3D

1. Generate grid, construct desire shape
2. Define material properties
3. Specify boundary and initial condition



Make initial stress balance



Set new condition which you want to simulate



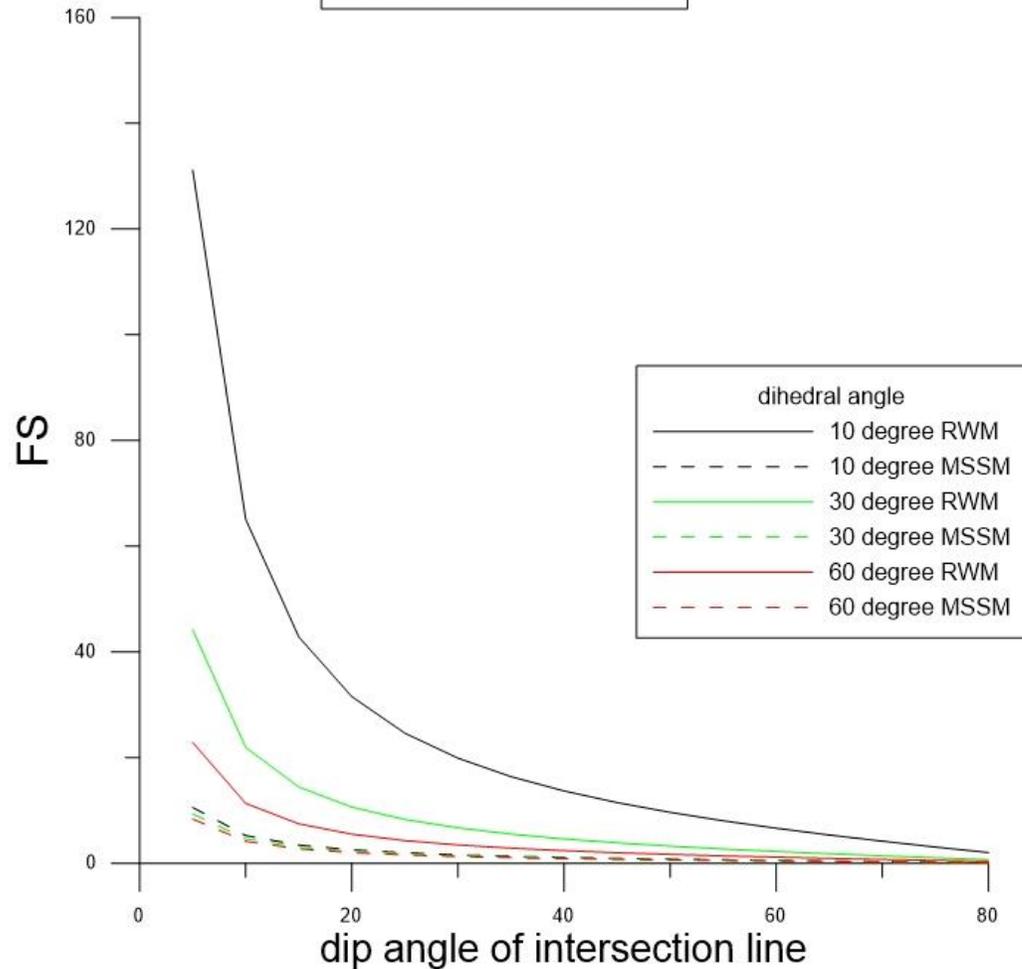
solve

Construct analysis model

Simulate and get solution

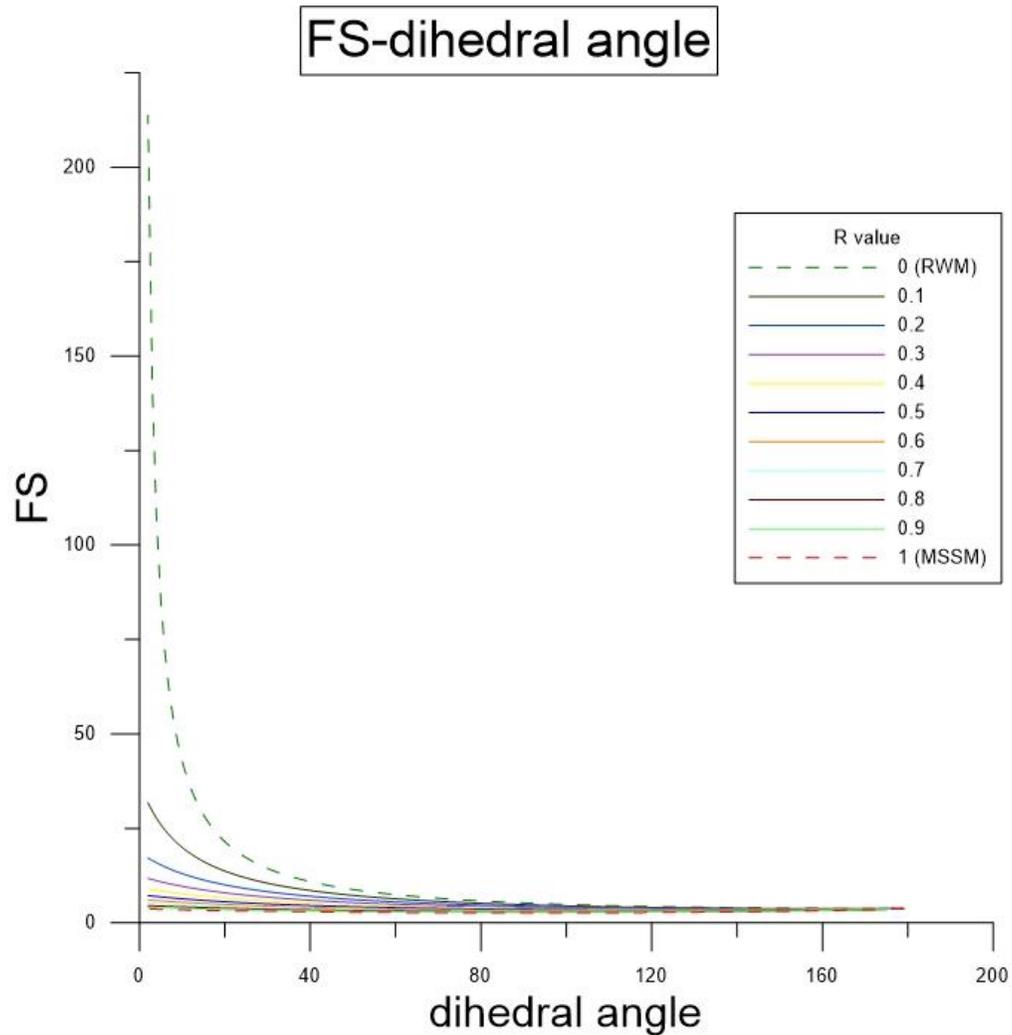
Preliminary result

FS-dip angle of intersection line



parameter	value
$P=W$	530 T
$C_a = C_b$	0
θ	0 degrees
$\varphi_a = \varphi_b$	45 degrees
Set $\alpha = \beta$, dihedral angle= $180-(\alpha + \beta)$	

Preliminary result



- $T' = RT_{max}$
- (R=0-1)

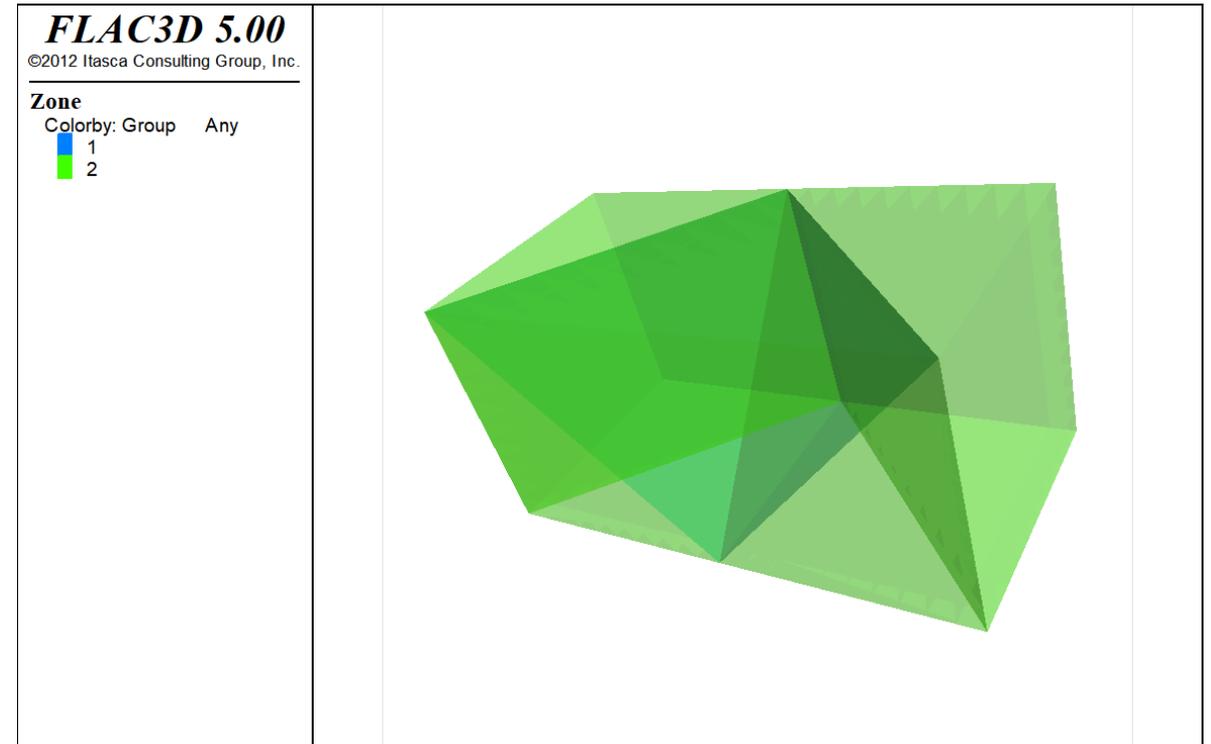
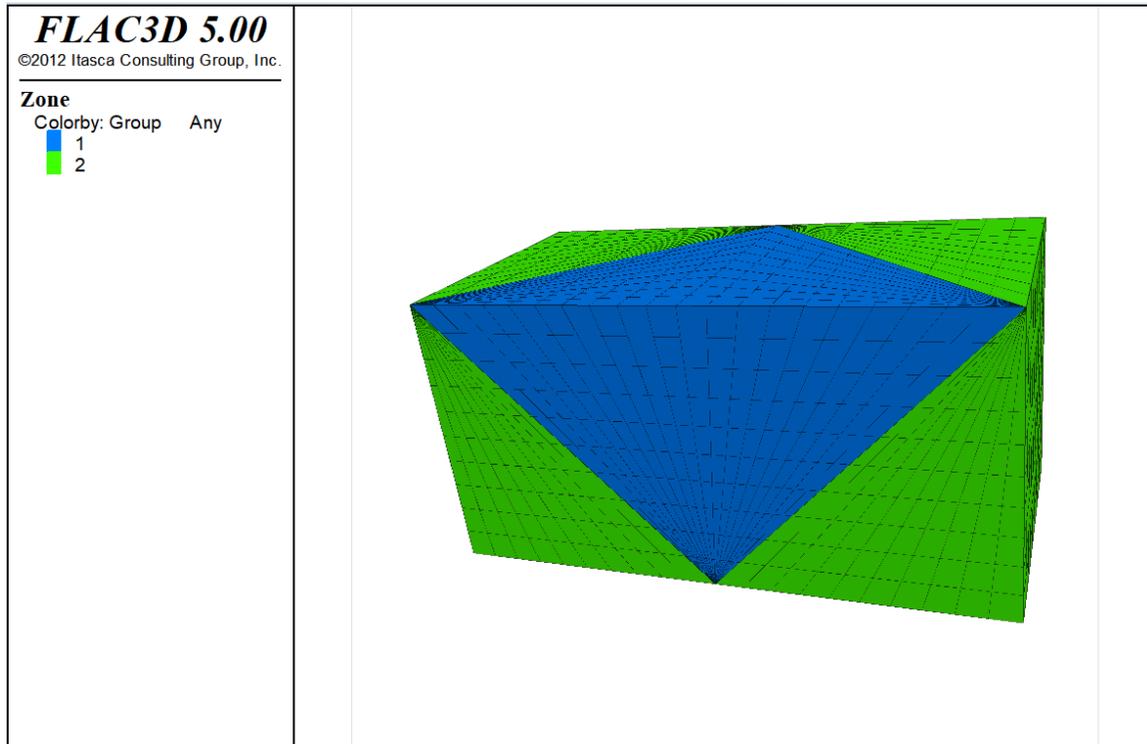
parameter	value
P=W	530 T
γ	15 degrees
$C_a = C_b$	0
θ	0 degrees
$\varphi_a = \varphi_b$	45 degrees
Set $\alpha = \beta$, dihedral angle=180-($\alpha + \beta$)	

Preliminary summary

1. When plunge of sliding wedge is small, FS has larger difference between RWM and MSSM.
2. When plunge of sliding wedge is fixed and dihedral angle is small, if we increase shear stress which is perpendicular to I-line a little from zero, the influence is very significant.

Future work

- Construct model by using Flac3D.
- Set different deformation to get solution.



Thanks for listening