



# 應用地質研究所

Graduate Institute of Applied Geology, NCU, Taiwan



## The Influence of JRC and Surface Geometry on the Mechanical/Hydraulic Aperture of 3D Printed Joints

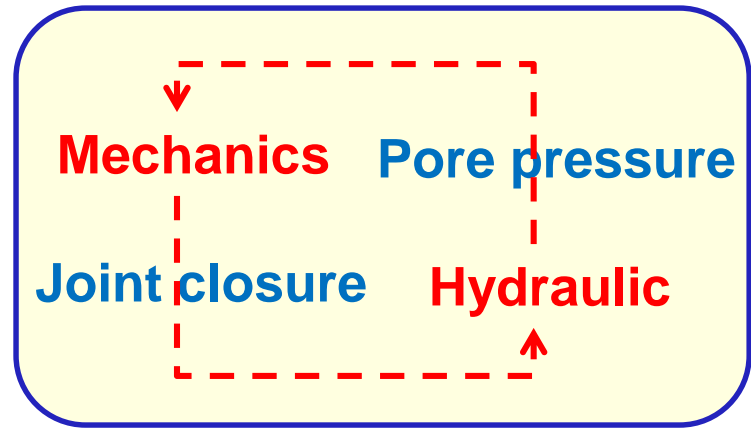
Presenter: Tan-Minh Le

Advisor: Prof Jia-Jyun Dong

Date: 2022/04/15

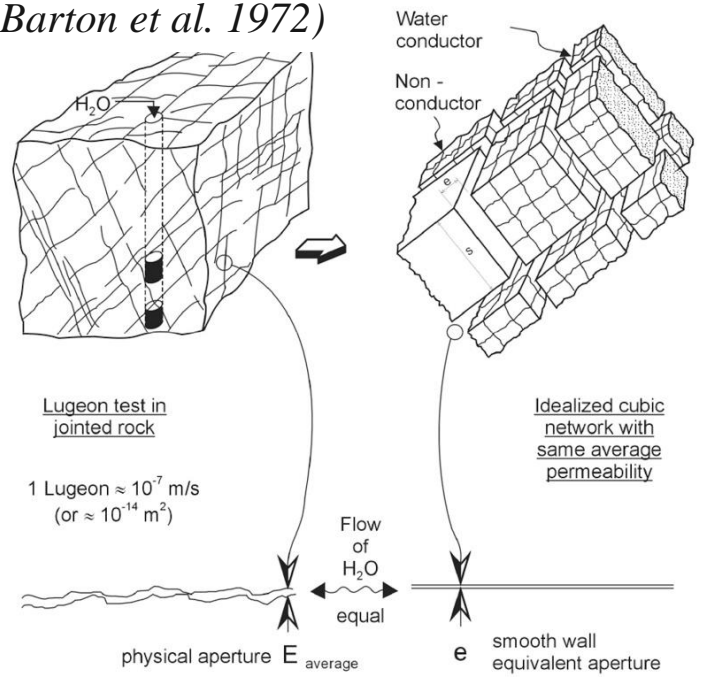
Seminar Presentation

Factors influent **Hydromechanical Coupling** of jointed rock masses:



- **Characterization of the hydraulic and mechanical aperture** (including the laboratory and in-situ test) still **critical** and **challenging** issues
- **Hydraulic aperture** is one of the **key source of uncertainty**

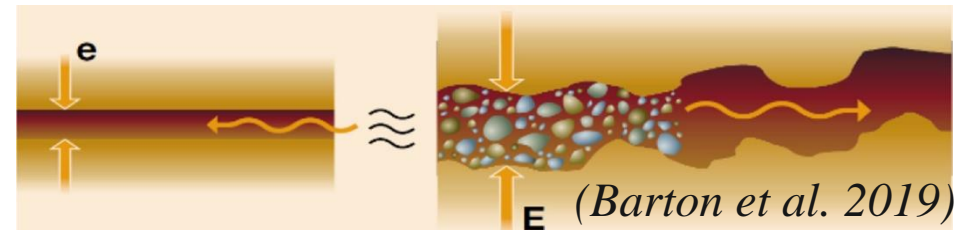
(Barton et al. 1972)



**e:** aperture accommodating a particular flux assuming a parallel plate model.

**E:** Mean physical distance between two fracture surfaces

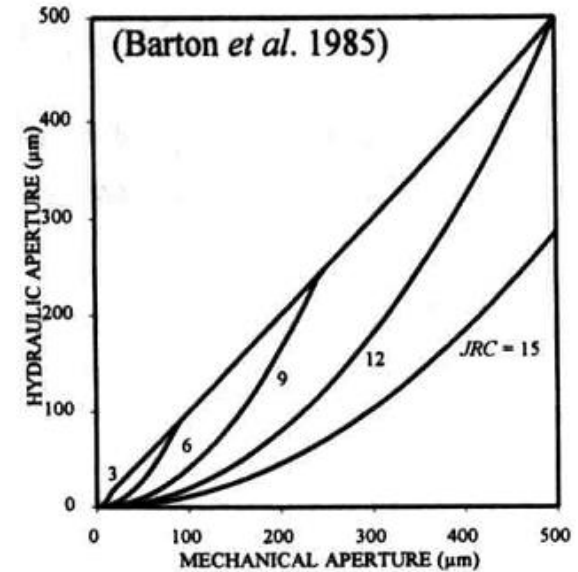
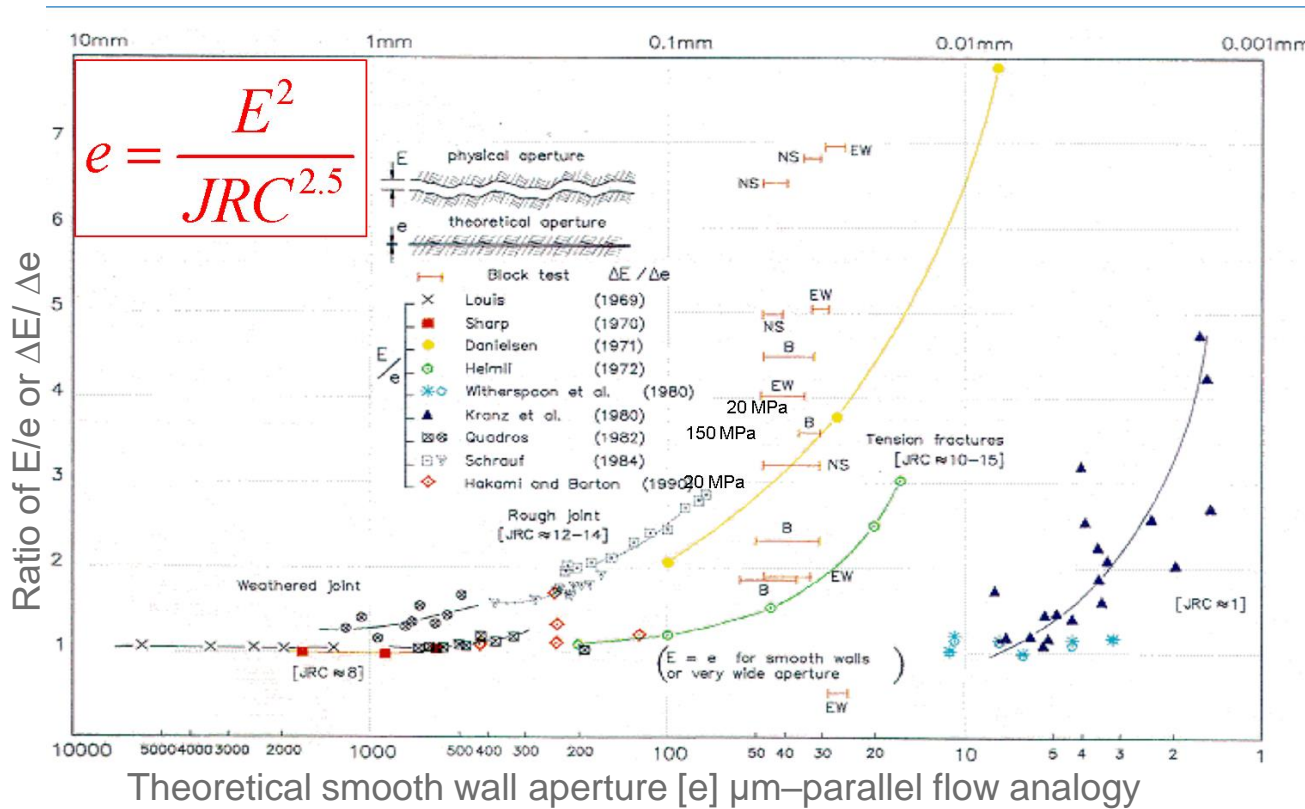
$$E \geq e$$



(Barton et al. 2019)

If two joints with the **same JRC**, will they have the **same Hydraulic Aperture and Mechanical Apertures**?

Synthetic joints created via 3D printer!!



- In which:.
- *JRC*: jointed roughness coefficient
  - *E*: Mechanical aperture ( $\mu\text{m}$ )
  - *e*: Hydraulic aperture ( $\mu\text{m}$ )

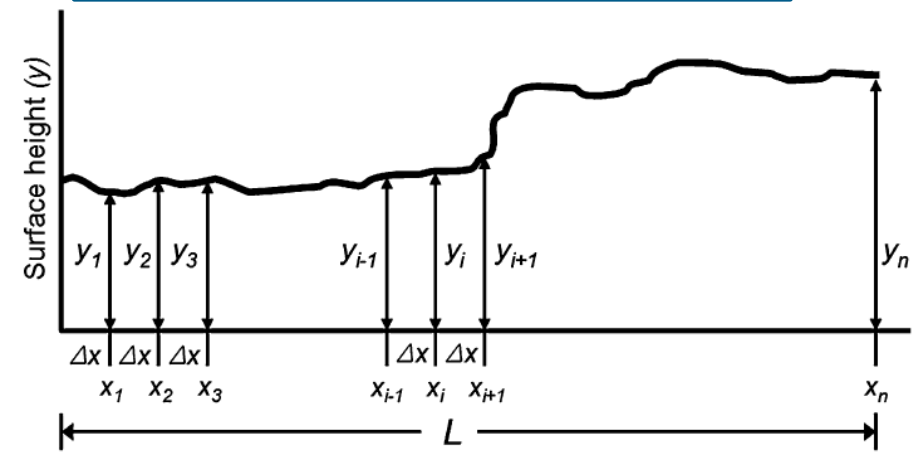
Constitutive model relating hydraulic aperture with mechanical aperture and joint roughness (*Barton et al. 1985*)

# Workflow

1. **Generate fracture 2D profiles**
2. **Import STL files into  
*Connex3 Objet260 Printer***
3. **3D printed samples**
4. **Morphology quantification**
5. **YOKO 2 measurement system**
6. **Data analysis and interpretation**

**Conclusion**

1. **Generate fracture 2D profiles**



$$JRC = 61.79 * Z_2 - 3.47$$

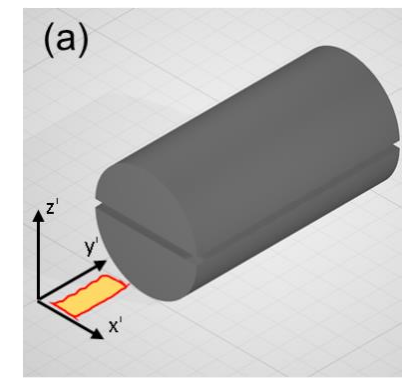
(Yu and Vayssade, 1991)

$$Z_2 = \left[ \frac{1}{L} \int_{x=0}^{x=L} \left( \frac{dy}{dx} \right)^2 dx \right]^{1/2} = \left[ \frac{1}{L} \sum_{i=1}^{n-1} \frac{(y_{i+1} - y_i)^2}{x_{i+1} - x_i} \right]^{1/2}$$

$$-0.25 \leq a \leq 0.25 \quad \text{for } 2 \leq JRC \leq 4$$

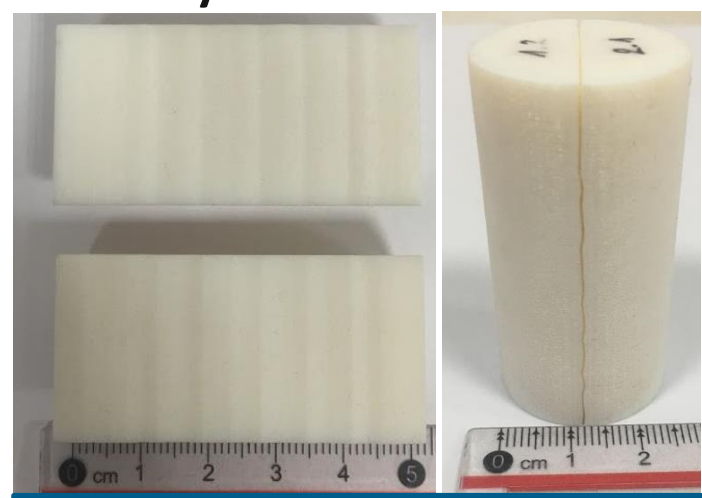
- a:** Asperity amplitude (mm)
- Z<sub>2</sub>:** root mean square first derivative of profile
- Δx:** sample interval (mm)

2. **Import STL files into Connex3 Objet260 Printer**

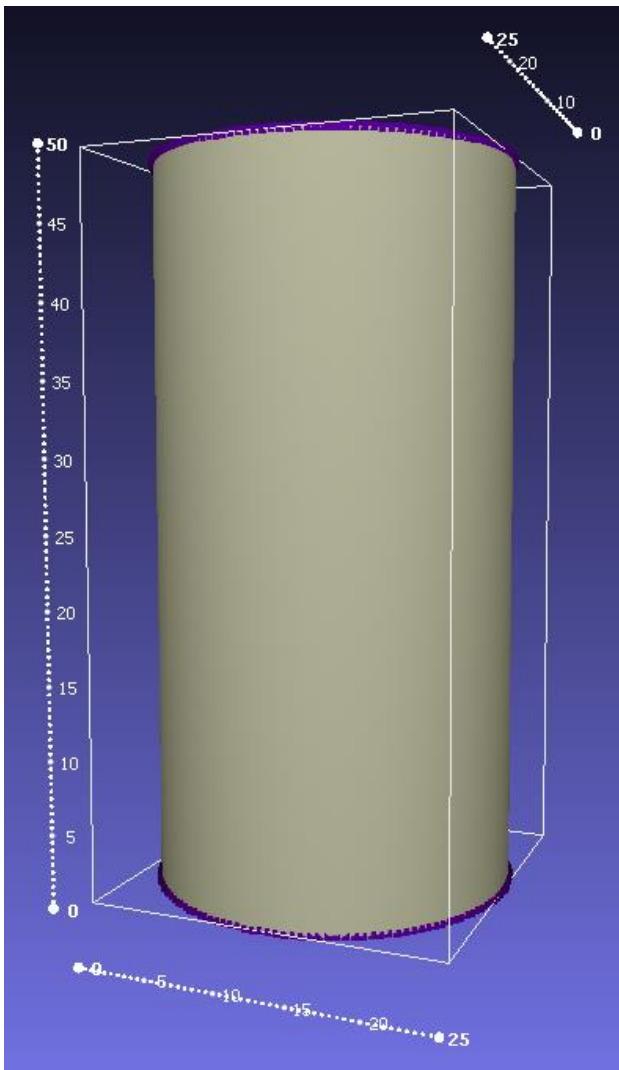


Printing directions

**Material:** **Vero Pure White** resin  
**Accuracy:** 0.2mm



3. **3D printed sample**



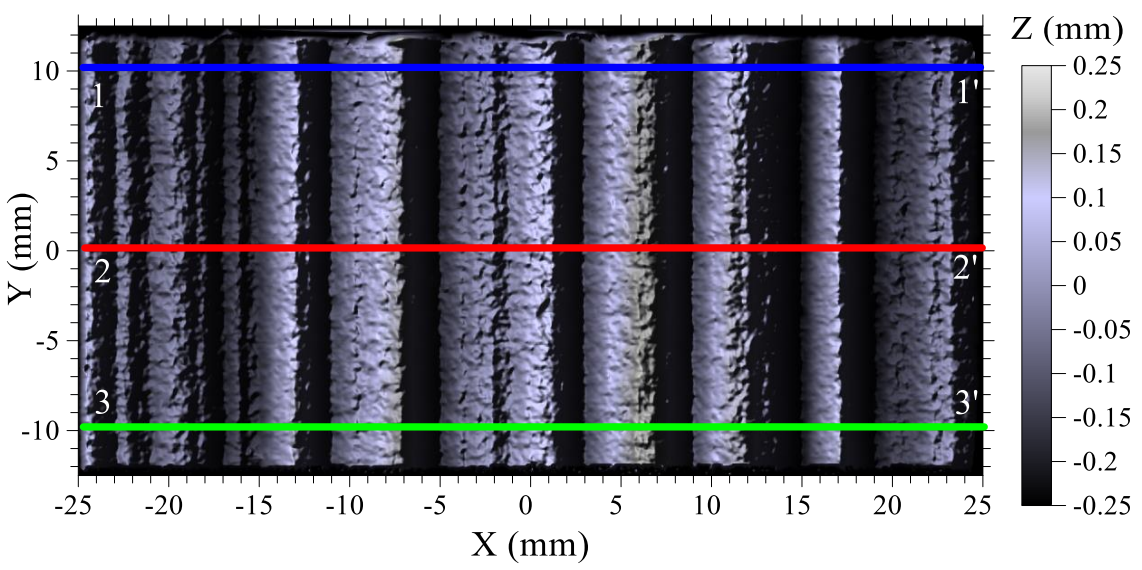
**Intact sample**

*Table 1. Geo-mechanical properties of Vero Pure White material compare with Granite*

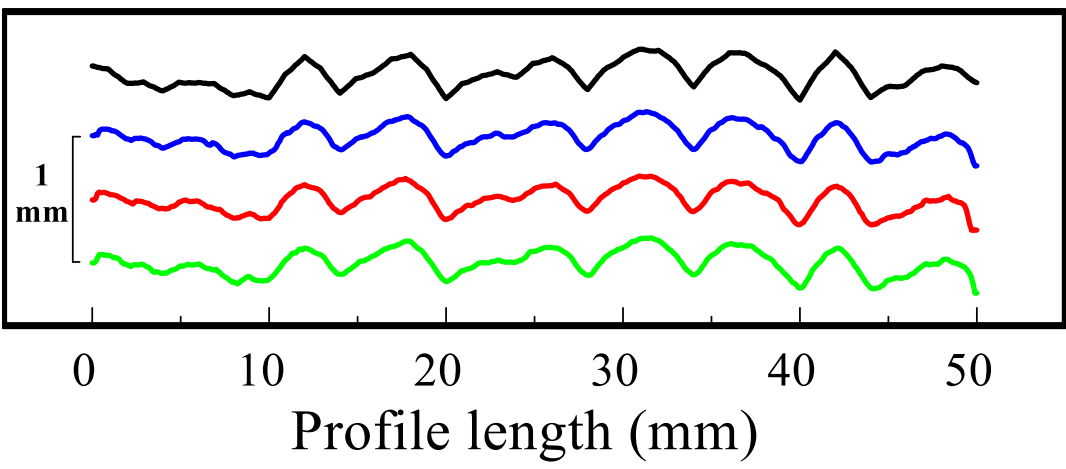
	<b>Vero Pure White</b>	<b>Granite</b>
<b>Density</b>	1.17 - 1.18 g/cm <sup>3</sup>	2.63 g/cm <sup>3</sup>
<b>Tensile strength</b>	50 - 65 MPa	18 MPa
<b>Flexural strength</b>	75 - 110 MPa	17 MPa
<b>Young's modulus</b>	2 - 3 GPa	20 - 75 GPa
<b>Water Absorption</b>	1.1 - 1.5%	0.36%



### 4. Morphology quantification



— P1-designed    — 1-1'    — 2-2'    — 3-3'



**HDI 120 ADVANCED 3D SCANNER**

Resolution (mm)	0.110-0.180
VDI/VDE Accuracy (mm)	0.06

**Figure .** HDI 120 advanced 3D scanner in Soil and Rock Mechanics Research Group at NCU, Taiwan

**Figure .** Scanned results of 3D-printed fracture surfaces (from P1\_Mat\_E1)

## 5. YOKO 2 measurement system

*(Dong et al. 2010)*

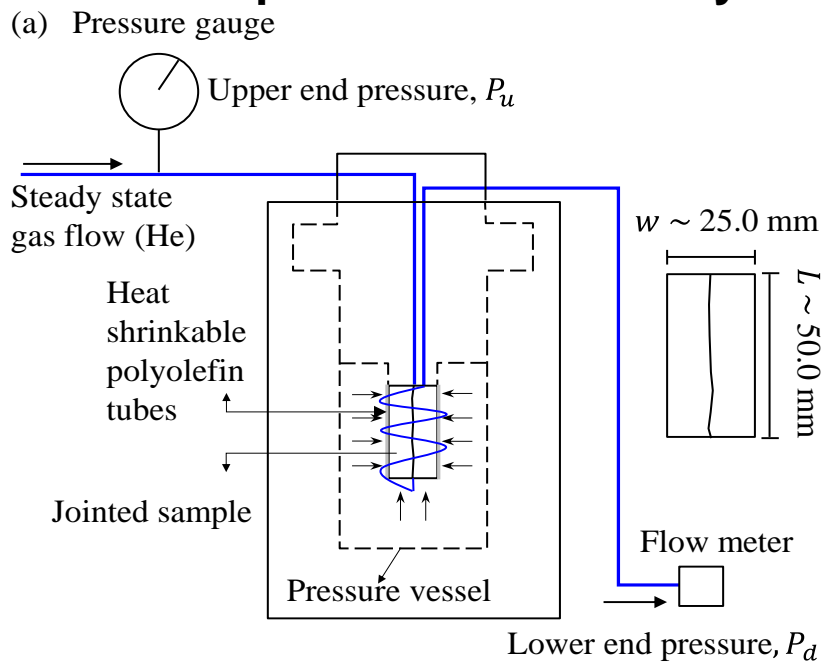


Soil and Rock Mechanics Research Group at NCU, Taiwan.

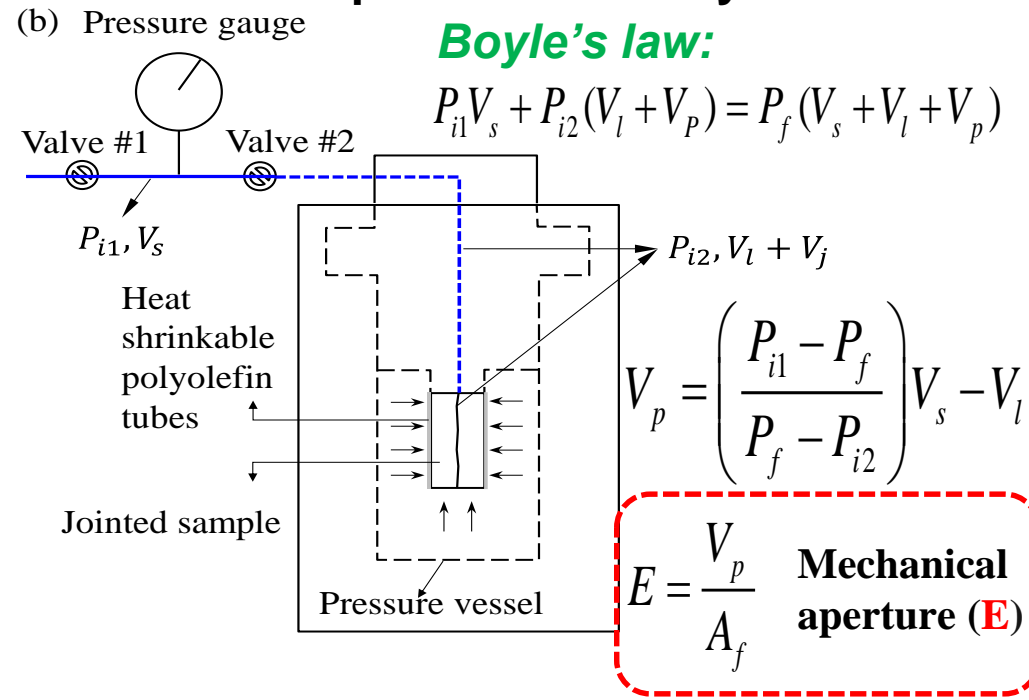
**Maximum confining pressure: 200MPa**



### Stress- dependent Permeability



### Stress- dependent Porosity



### For compressible flow (gas):

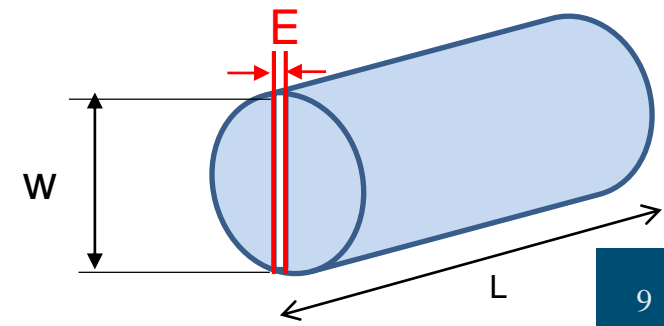
(Schrauf and Evans, 1986)

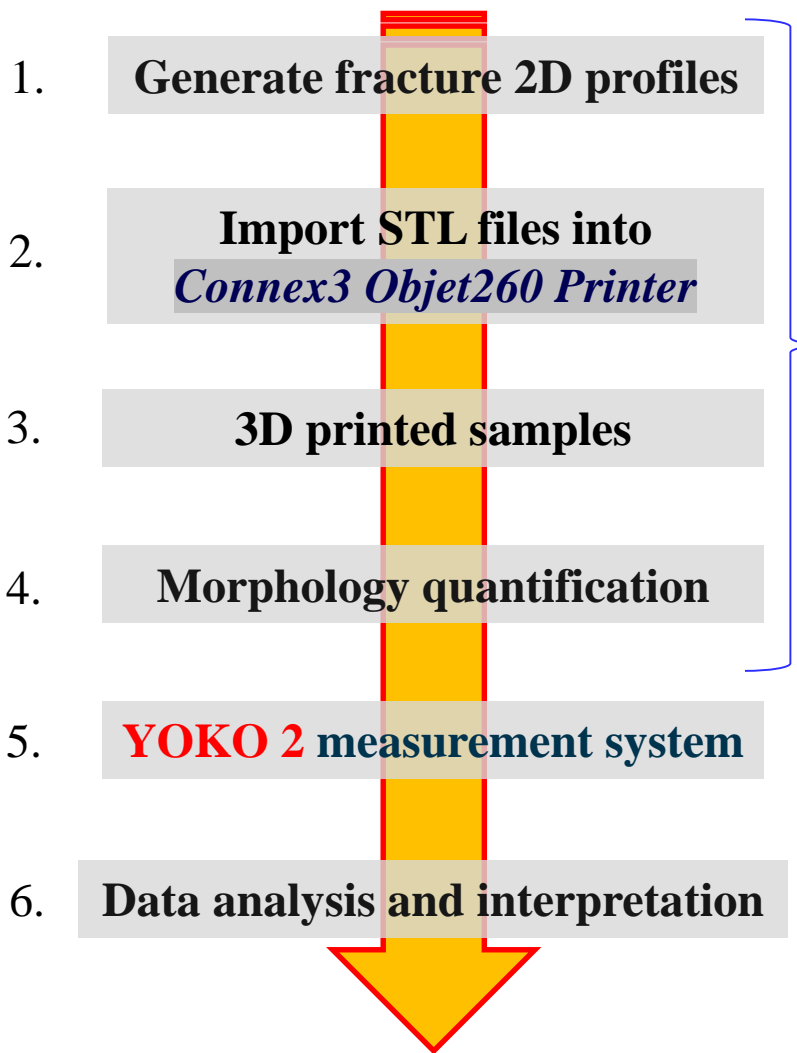
$$Q = \frac{e^3 \rho g w}{12 \mu} \frac{(P_u^2 - P_d^2)}{2 P_d L}$$

- $Q$ : volumetric flow rate ( $m^3/s$ )
- $e$ : hydraulic aperture (m)
- $\rho$ : helium gas density ( $kg/m^3$ )
- $g$ : acceleration of gravity ( $m/s^2$ )
- $w$ : joint width (m)
- $\mu$ : viscosity (Pa.s)
- $P_u$ : upper pressure (Pa)
- $P_d$ : atmospheric pressure (Pa)
- $L$ : joint length (m)

### Hydraulic aperture (e):

$$e^3 = \frac{24 \mu L P_d Q}{w(P_u^2 - P_d^2)}$$





## Advantages

### Constraint system:

Surface roughness,  
Repeatability of samples  
and experiment results

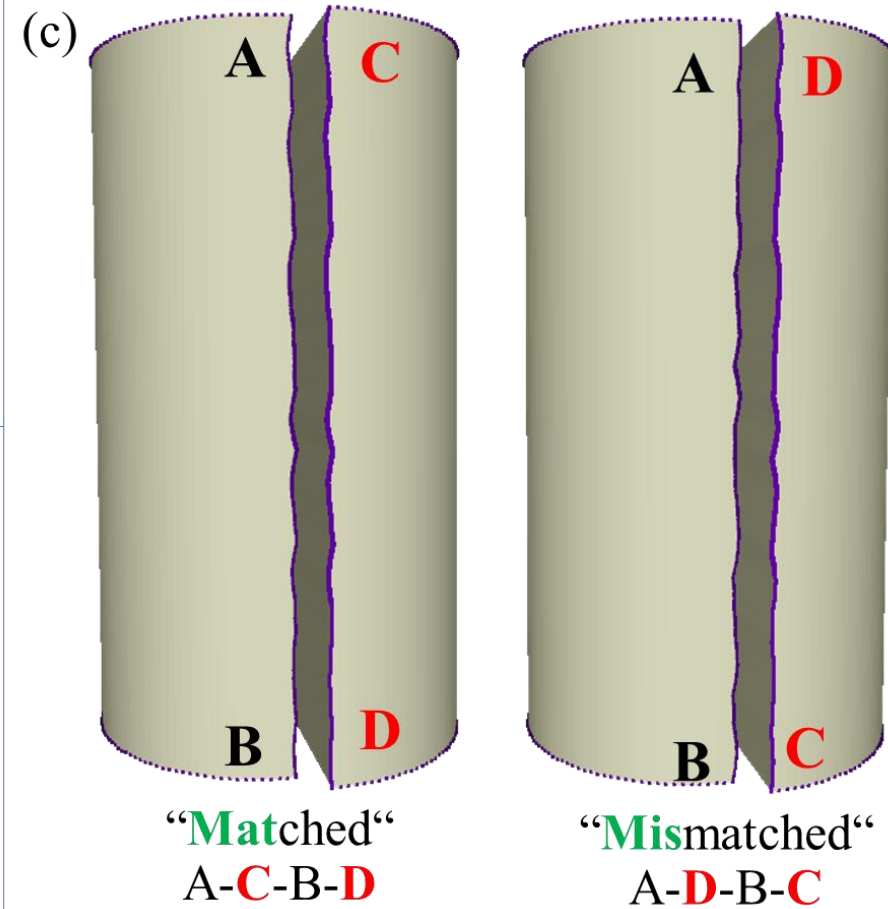
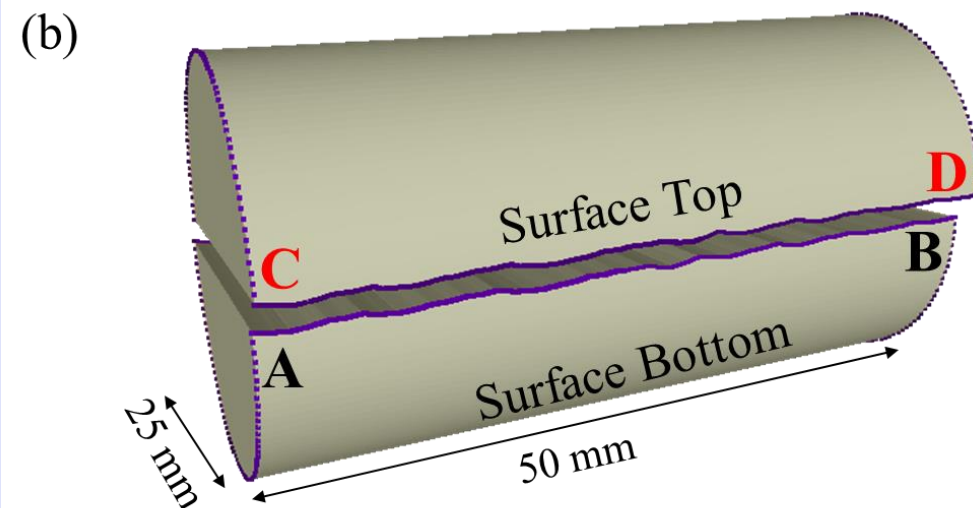
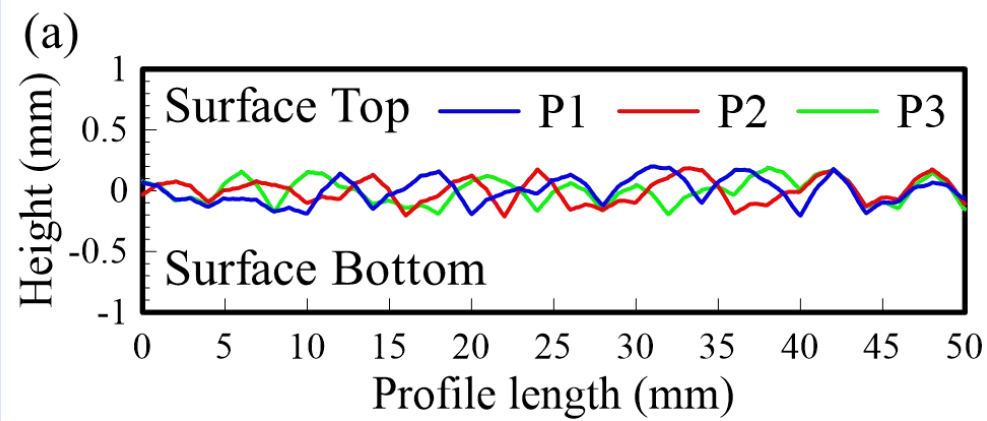
## Limitations

Printing period, Printing direction

## Conclusion

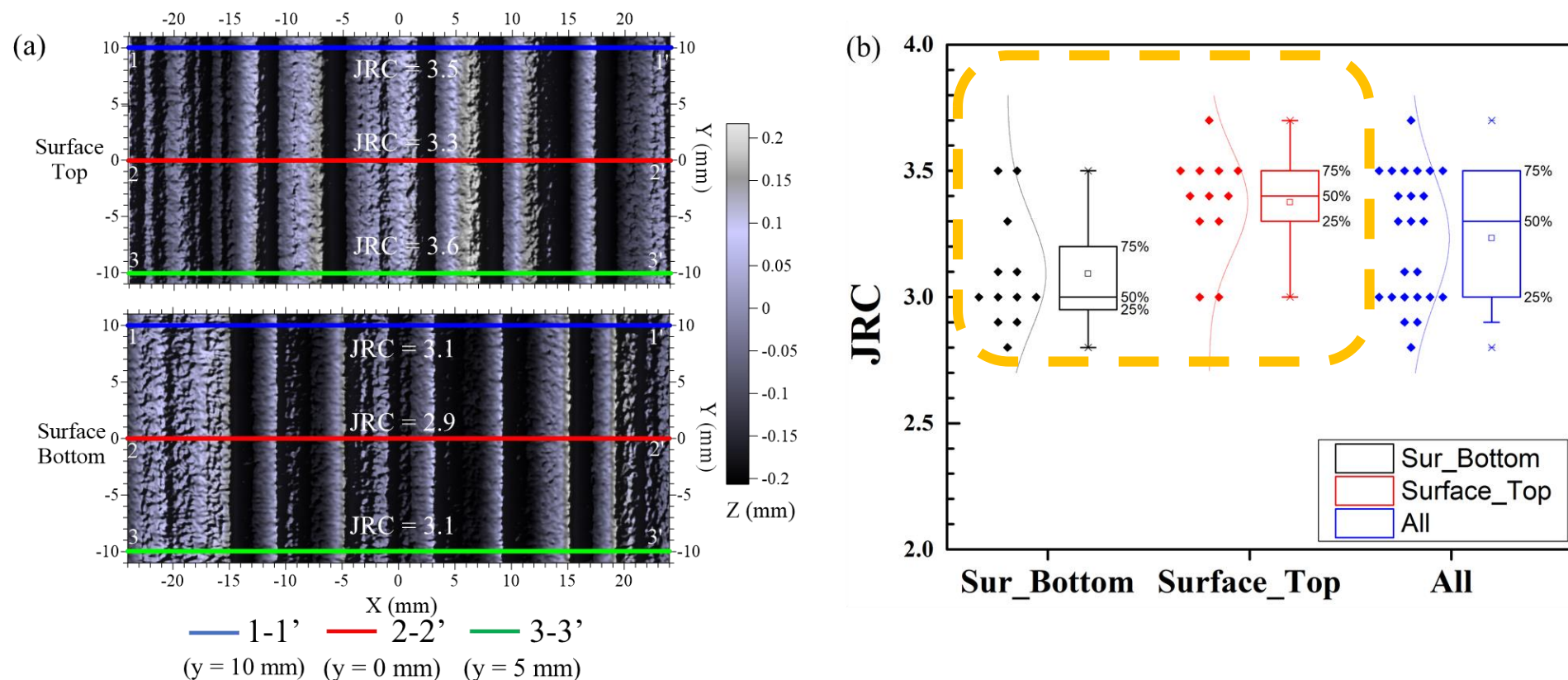
# Sample Creation

**3** generated rough fracture surfaces (**JRC = 3.5**)



3D view of cylinder single joint sample P1\_Mat\_ABDC

# Scanned results of the printed samples



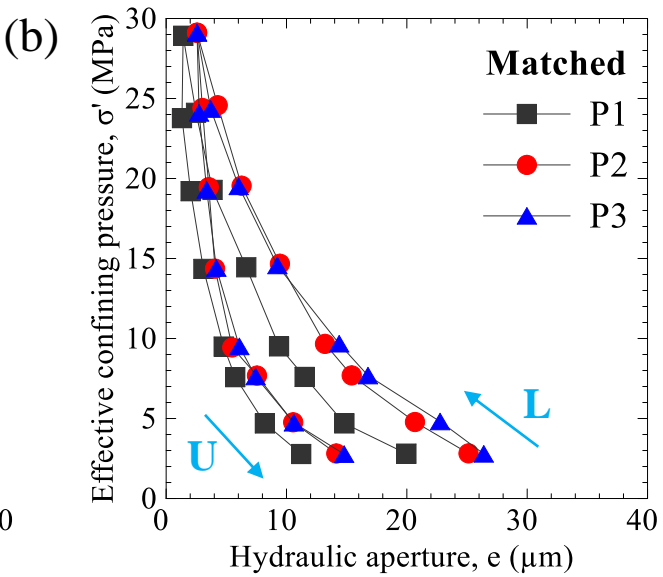
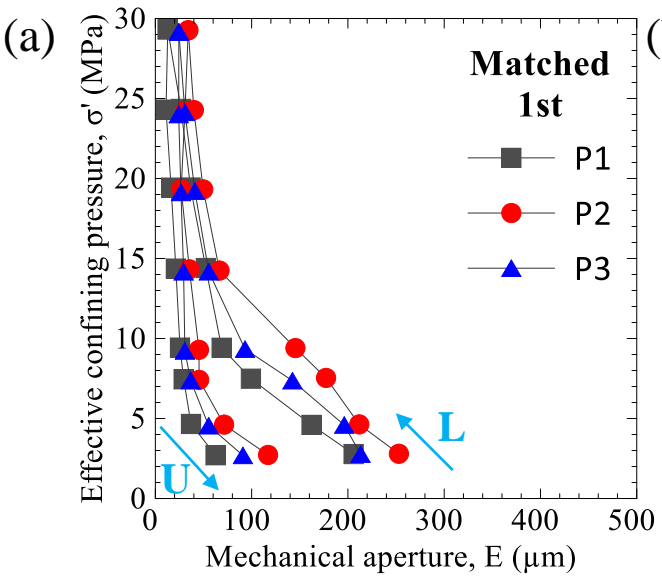
**Figure .** (a) Scanned results of 3D-printed fracture surfaces (from P1\_Mat\_E1)

(b) Boxplots for mean JRC all samples, with the central red line representing the median, and the box edges and whiskers denoting the interquartile, and the 5<sup>th</sup> to 95<sup>th</sup> percentile range, respectively

$E$  vs  $\sigma'$  Matched samples

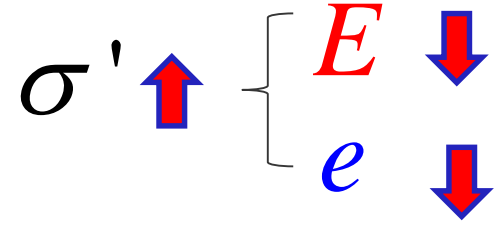
$e$  vs  $\sigma'$

Experimental results

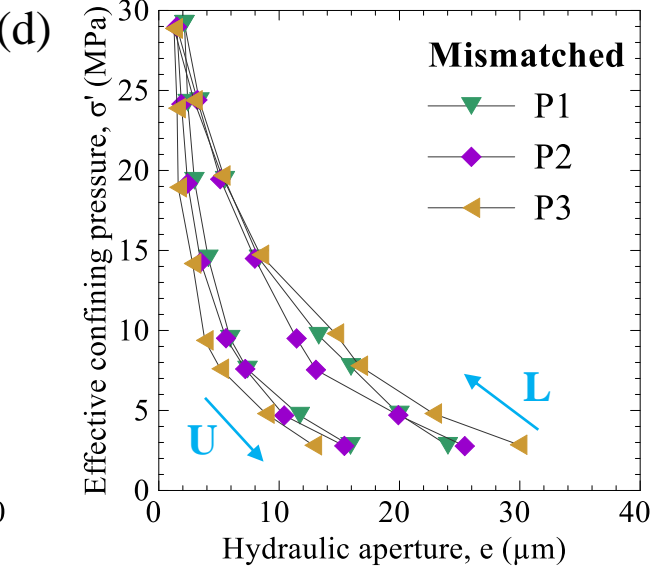
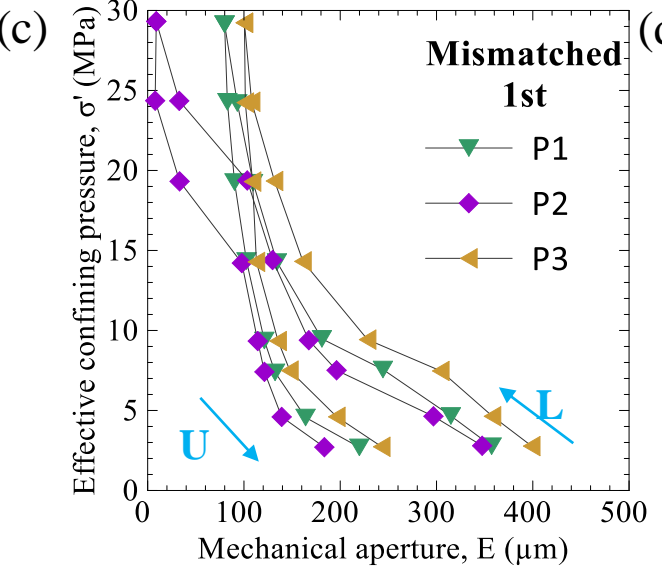


$E$  vs  $\sigma'$ ;  $e$  vs  $\sigma'$

□ nonlinear relationship



Mismatched samples



□ Factors affect: ???

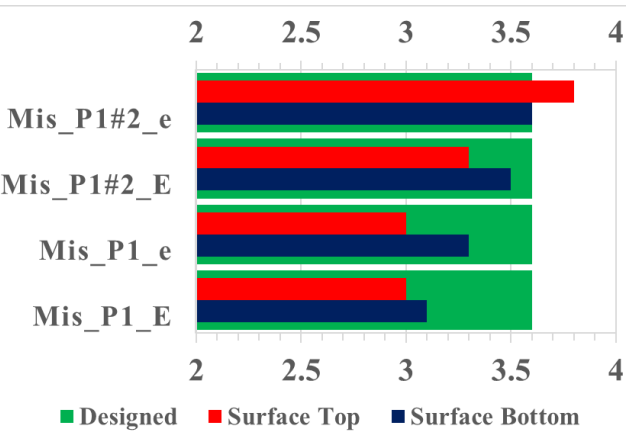
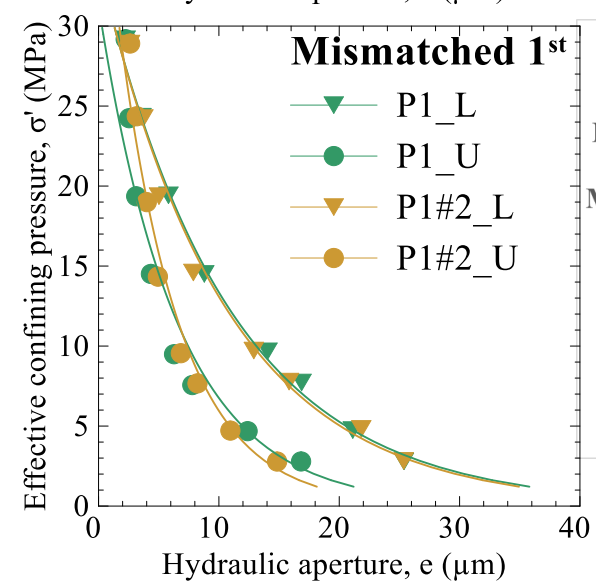
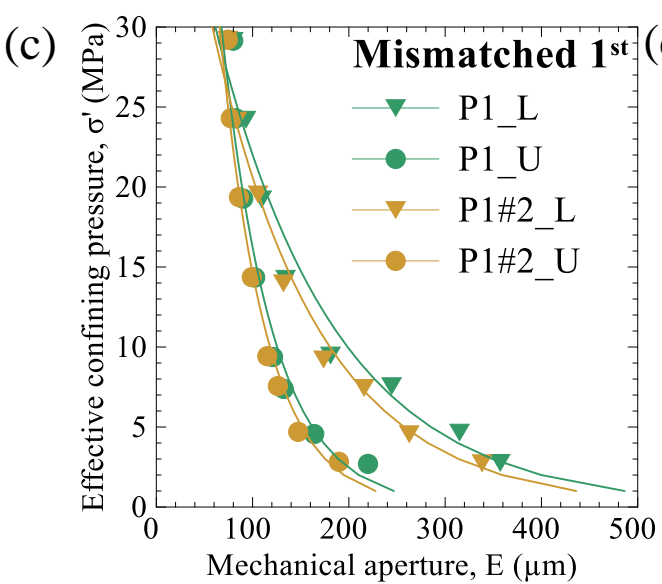
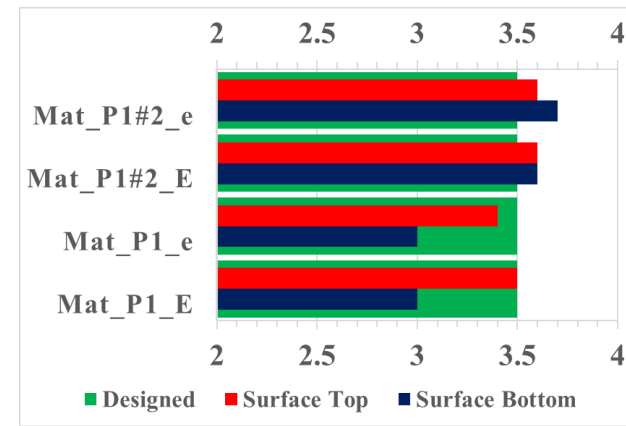
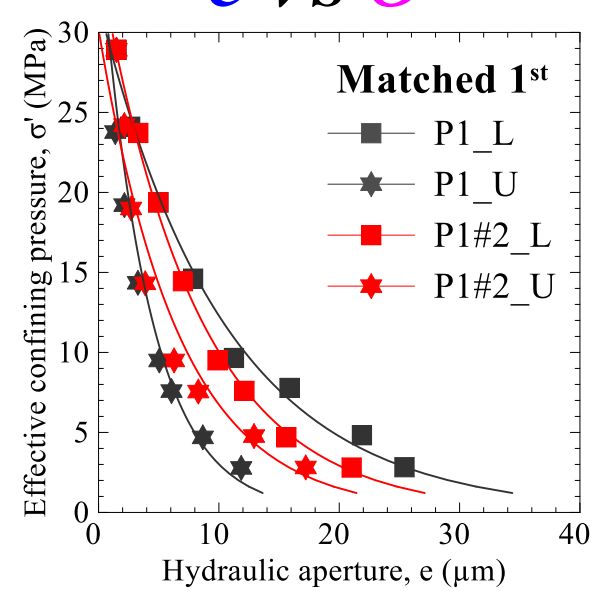
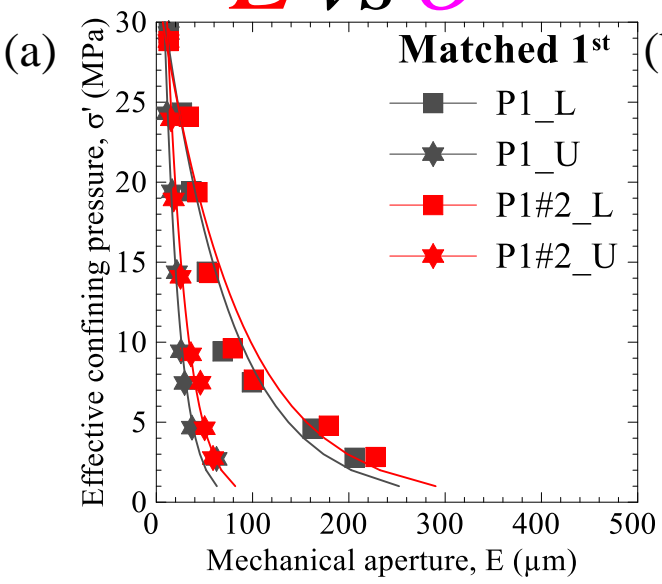
□ P2\_Mis displays noticeably lower  $E$



# Reproducibility

$E$  vs  $\sigma'$

$e$  vs  $\sigma'$



## Semi-logarithmic closure law (*Evans et al., 1992*)

$$\ln(\sigma_n') = \ln(\sigma_n^{ref}) + \Delta E_n * (dk_n / d\sigma_n')$$

$$\text{Fit\_Loading Eq: } E_i - \frac{\ln(\sigma_n' / \sigma_n^{ref})}{\left( \frac{dk_n}{d\sigma_n'} \right)}$$

In which:

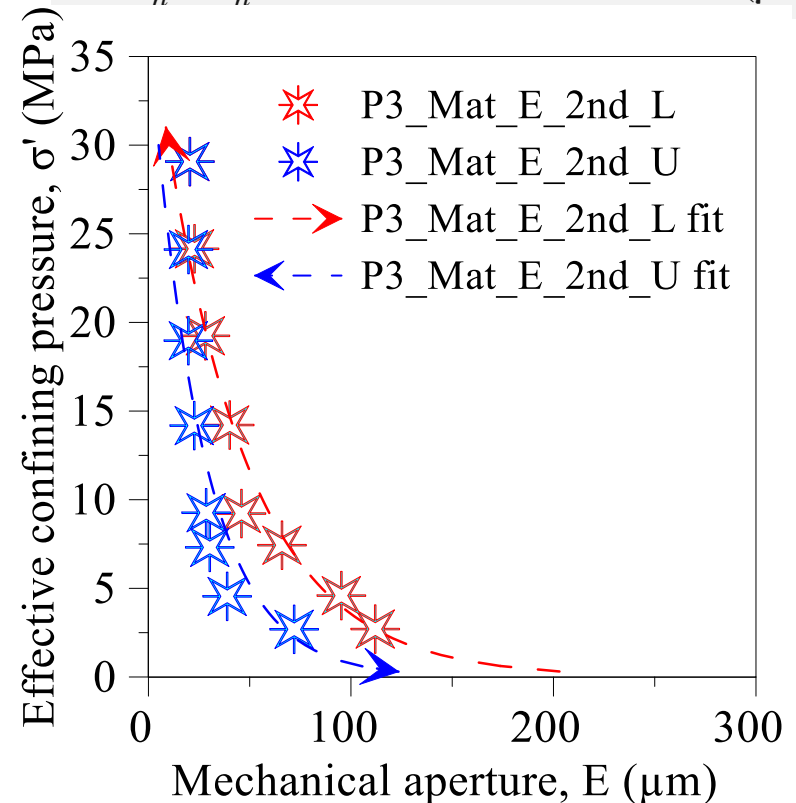
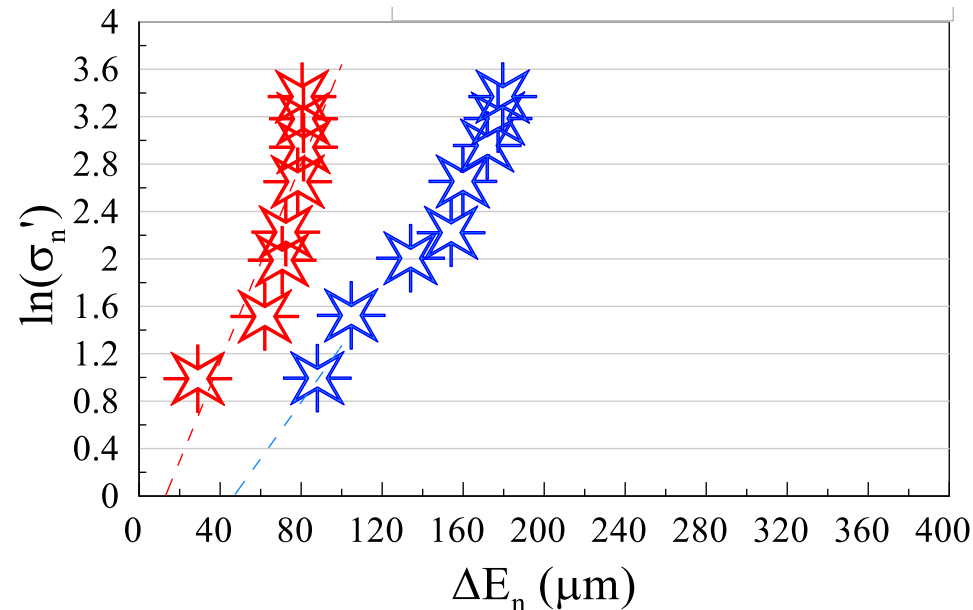
$\sigma_n'$  : effective stress (MPa)

$\sigma_n^{ref}$  : reference effective stress (MPa)

$E_i$  : initial aperture at  $\sigma_n^{ref}$  ( $\mu\text{m}$ )

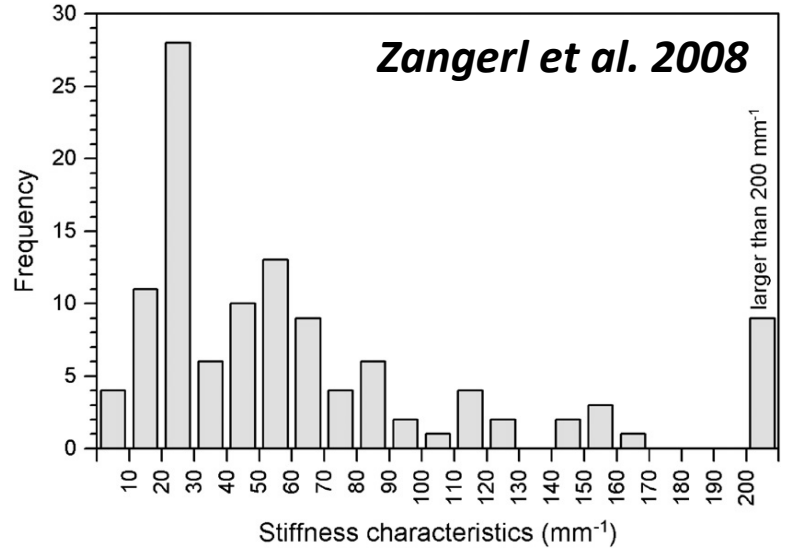
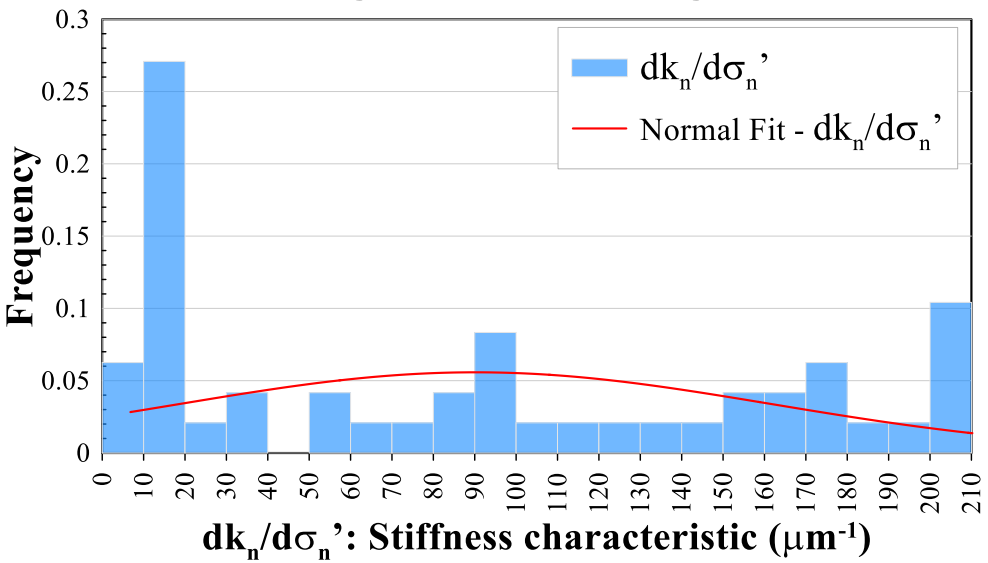
$\Delta E_n$  : Joint closure ( $\mu\text{m}$ )

$dk_n/d\sigma_n'$  : Stiffness characteristic ( $\mu\text{m}^{-1}$ )

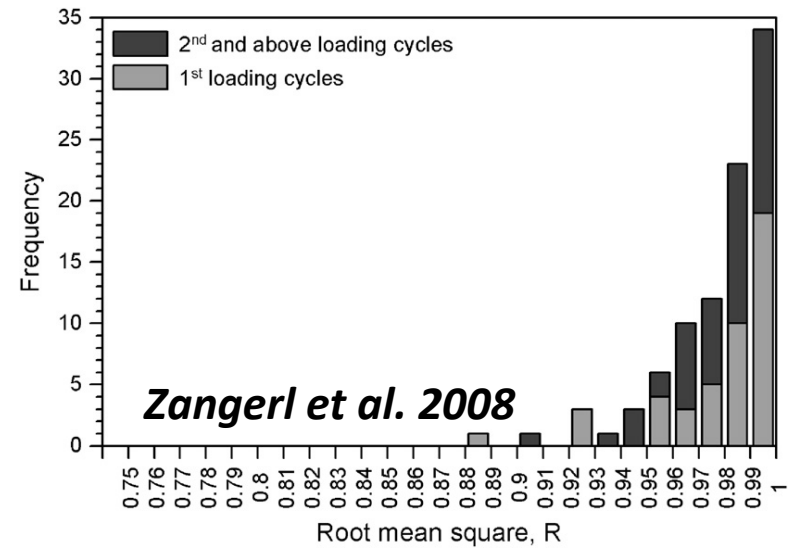
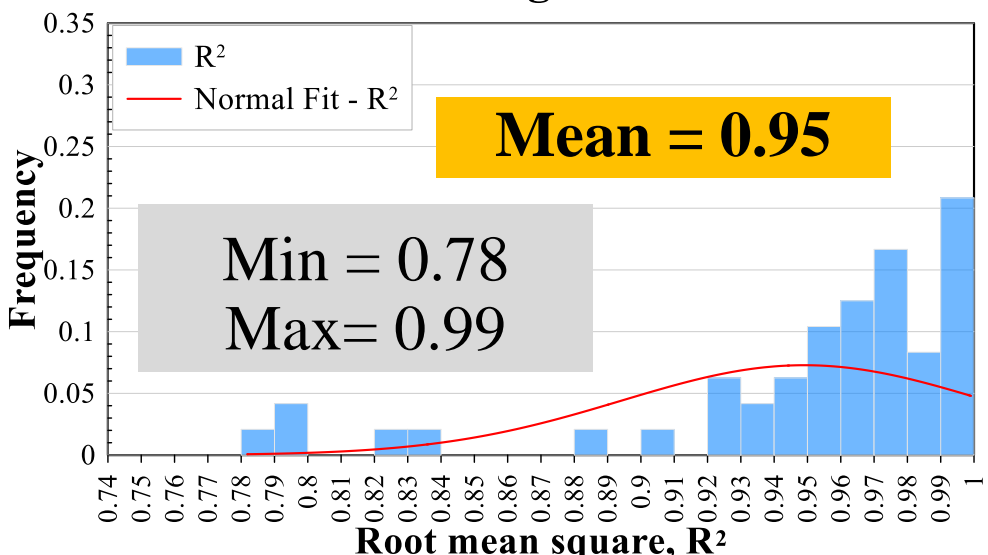


# Applicability to natural fracture stiffness

## Semi-logarithmic Histogram



## R<sup>2</sup> Histogram



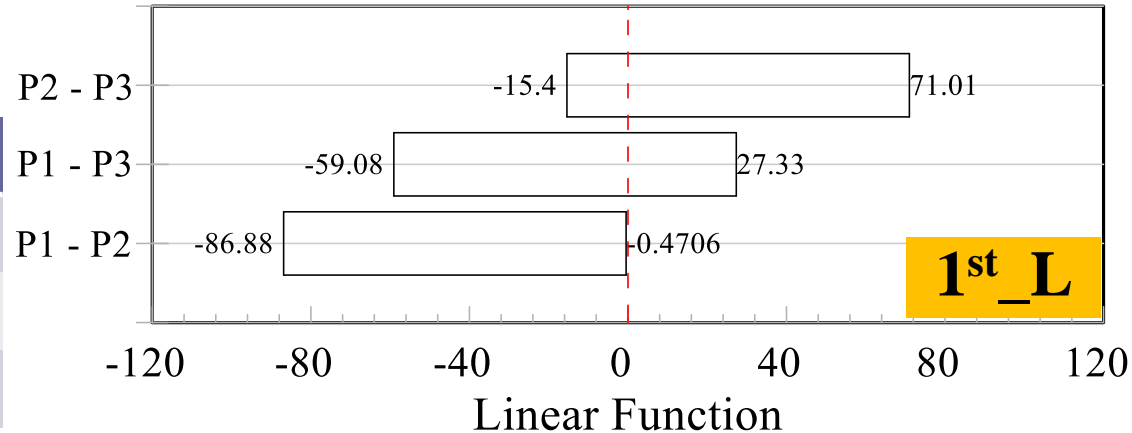
# ANOVA test *MAT* samples

## Compare *E*

### Post hoc Test Tukey HSD

Data analyzed	Sig. results
P2 – P3	p = 0.344
P1 – P3	p = 0.777
P1 – P2	<b>p = 0.046</b>

### 95% family-wise confidence level Tukey HSD



The mean differences between two groups(µm)

- ❑ P2 mean is **significantly different** at the 5% level of significance for P1

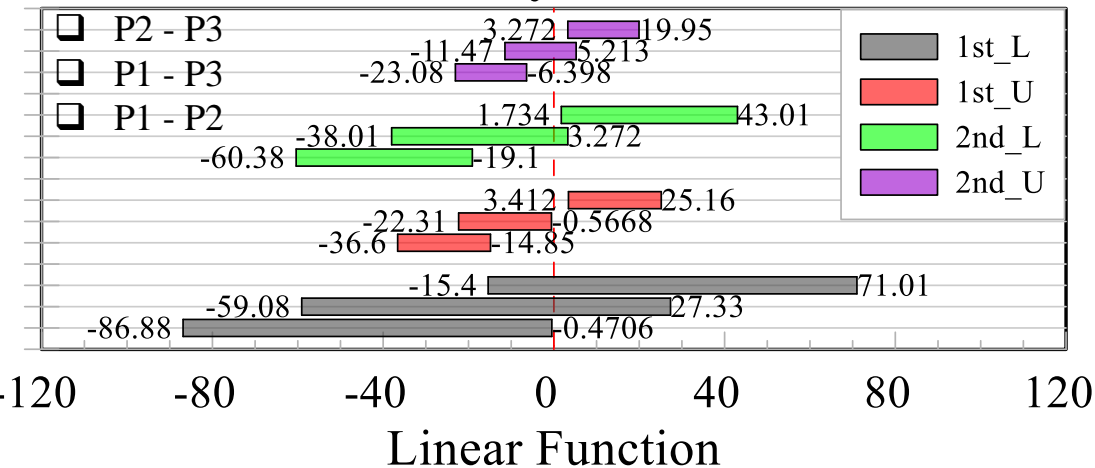
# ANOVA test *MAT* samples

E

e

95% family-wise confidence level

Tukey HSD



The mean differences between two groups ( $\mu\text{m}$ )

- P2 mean is **significantly different** at the 5% level of significance between P1 and P3 (at **1<sup>st</sup>\_U**, **2<sup>nd</sup>\_L**, **2<sup>nd</sup>\_U**)

Data analyzed

ANOVA results

1<sup>st</sup>\_L

p=0.337

1<sup>st</sup>\_U

p=0.288

2<sup>nd</sup>\_L

p=0.111

2<sup>nd</sup>\_U

p=0.335

- **Sig>0.05** => There are **no statistically different** in hydraulic aperture.

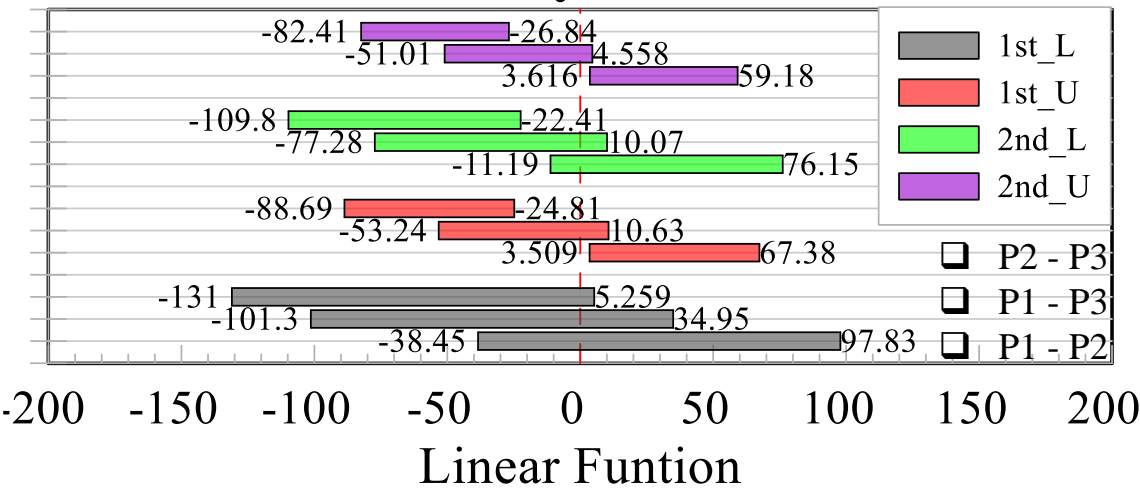


# ANOVA test *MIS* samples

**E**

**e**

**95% family-wise confidence level  
Tukey HSD**



The mean differences between two groups(g)

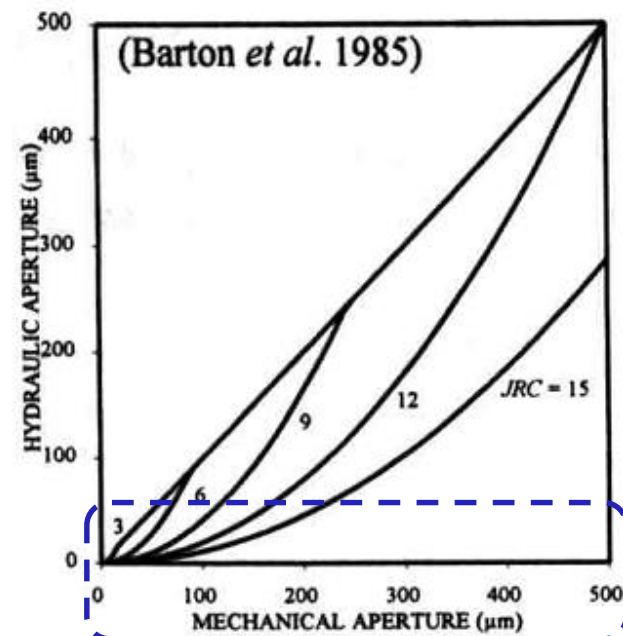
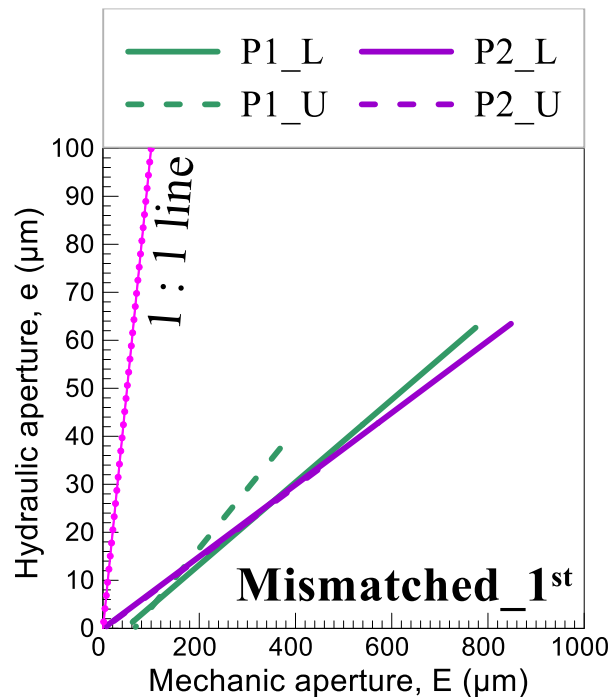
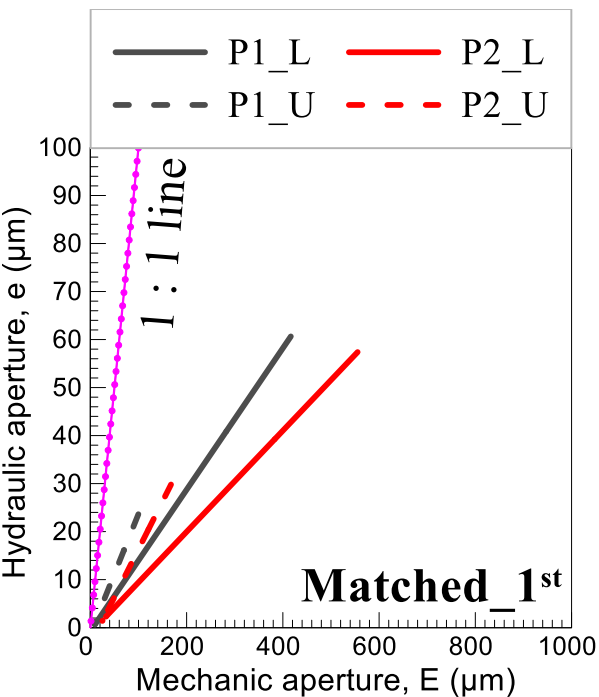
- **P2** mean is **significantly different** at the 5% level of significance between P1 and P3 (at **1<sup>st</sup>\_U**, **2<sup>nd</sup>\_L**, **2<sup>nd</sup>\_U**)

Data analyzed	ANOVA results
1 <sup>st</sup> _L	p=0.966
1 <sup>st</sup> _U	p=0.151
2 <sup>nd</sup> _L	p=0.135
2 <sup>nd</sup> _U	p=0.143

- **Sig>0.05** => There are **no statistically different** in hydraulic aperture.

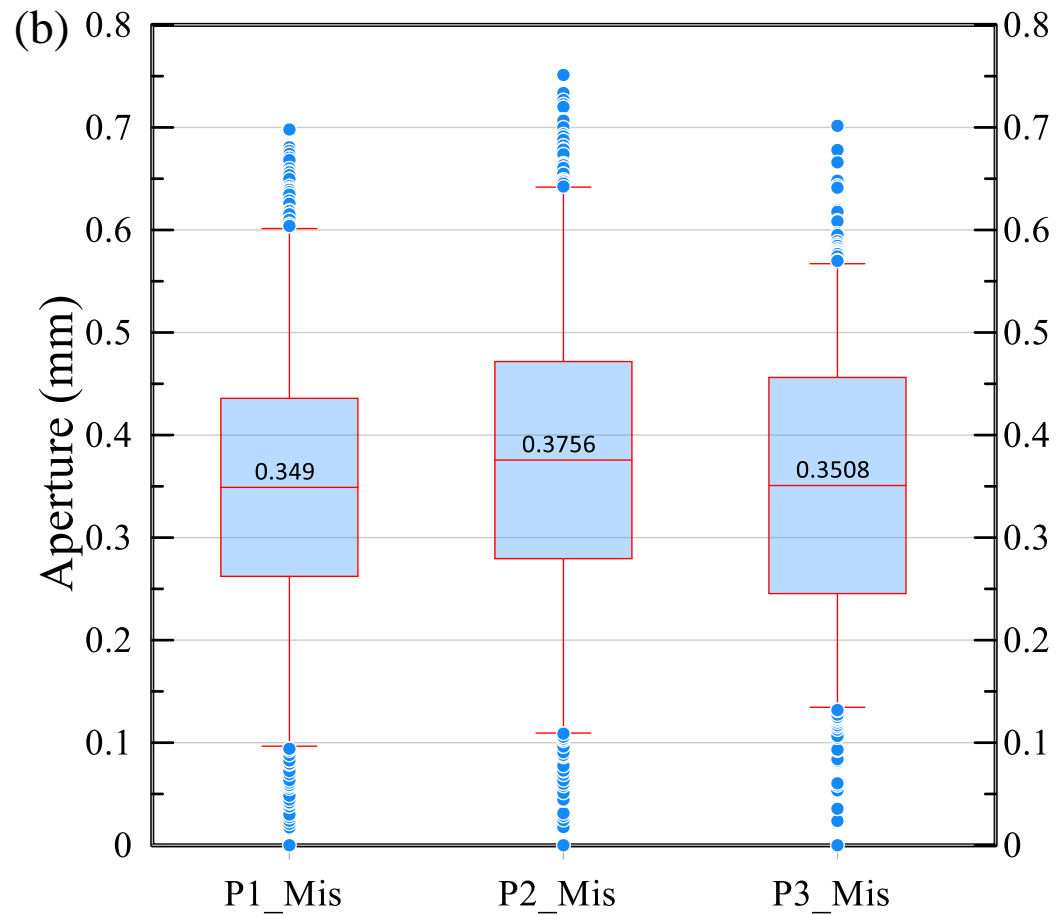
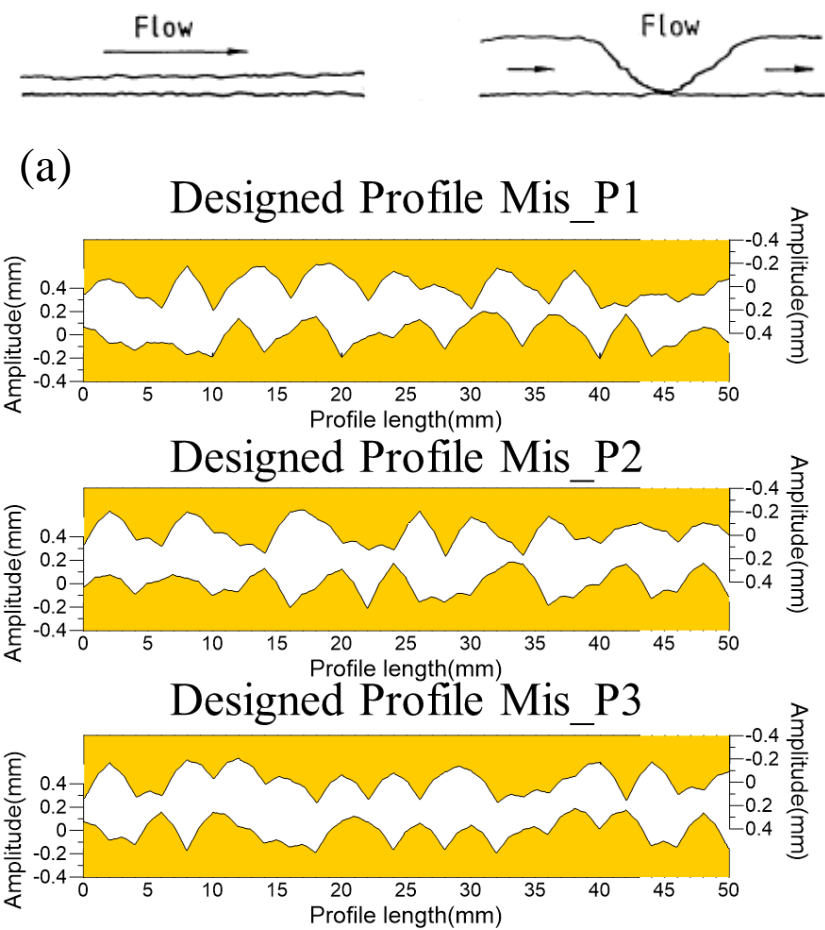
# \*\*\*\*\* e vs E relation

## 1<sup>st</sup> cycle



$\equiv$  JRC  
 $\neq$  Profiles

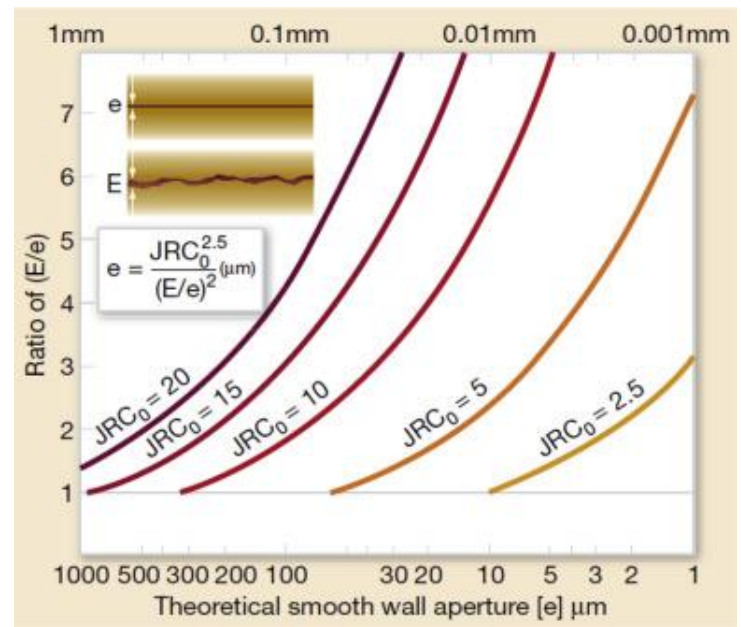
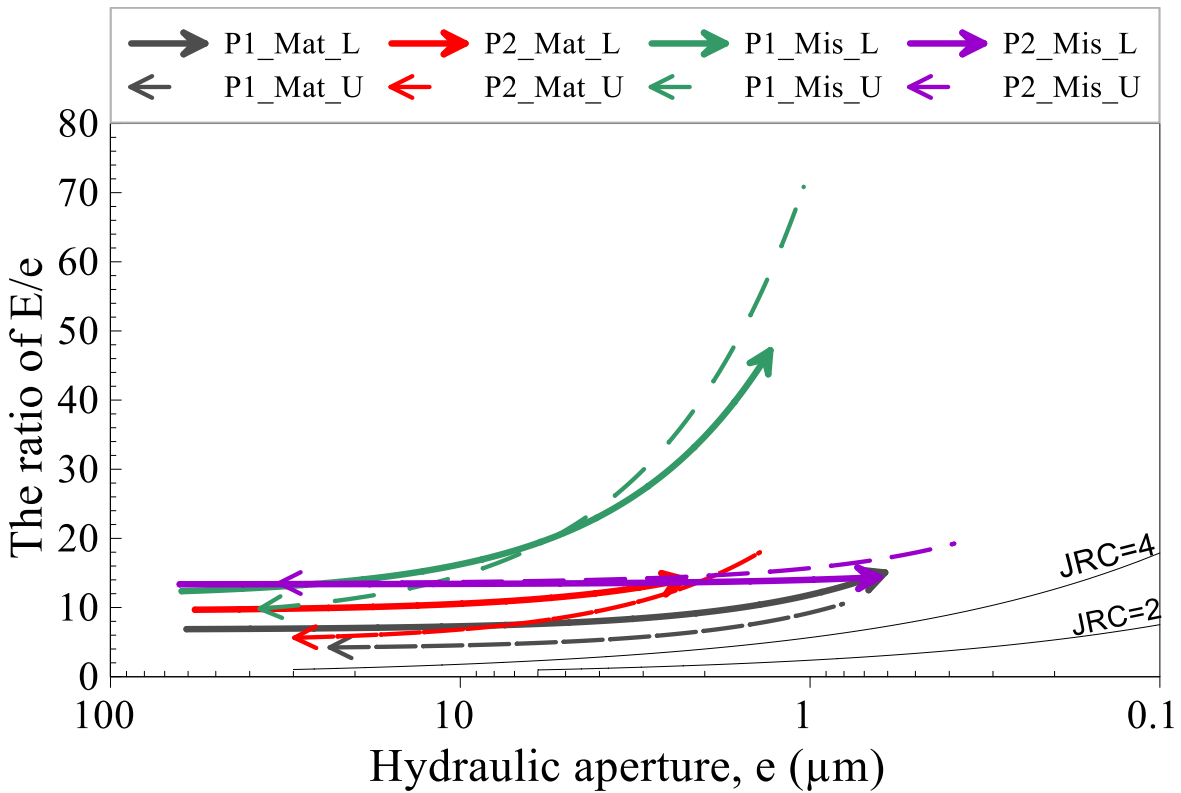
$E \neq$   
 $e$



**Figure .** (a) Fracture aperture along the mismatched surfaces  
 (b) Boxplots for each mismatched profile , with the central red line representing the median, and the box edges and whiskers denoting the interquartile, and the 5<sup>th</sup> to 95<sup>th</sup> percentile range, respectively

\*\*\*\*\* **e vs E relation**

1<sup>st</sup> cycle



(Barton et al. 2019)

≡ JRC  
≠ Profiles

**E<sub>Mis</sub> ≠**  
**e ≅**

➤ Same JRC, ≠ Profiles  $\Rightarrow E \neq, e \cong$  (Mat and Mis)

- The experimental results indicate that there are still uncertainties when using JRC to predict the relationship of E and e.
- 3D printed samples can be used to improve the understanding of natural subsurface fracture flow.
- E – e relation to other 3D-printed or natural joints requires further research



THANK YOU

